

## AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application.

### Listings of Claims:

1. (Currently Amended) An actuator assembly of a suspension, comprising:
  - a lever provided with first and second brackets and ~~hinged~~ hingedly connectable to a sub frame;
  - an actuator coupled to the first bracket on one end thereof; and
  - a movable member provided on the an outer circumferential surface ~~permitting pivoting~~ of the actuator, such that the actuator pivots about the movable member.
2. (Original) The actuator assembly as claimed in claim 1, wherein the movable member is a hinge unit mounted on the actuator.
3. (Currently Amended) The actuator assembly as claimed in claim 1, wherein the first bracket has an insert hole which ~~takes a~~ is circular in shape.
4. (Currently Amended) The actuator assembly as claimed in claim 2, wherein the first bracket has an insert hole which ~~takes a~~ is circular in shape.

5. (New) The actuator assembly as claimed in claim 1, wherein the first bracket is provided in one of a horizontal or vertical direction with respect to the lever and the second bracket is provided in the other of the horizontal or vertical direction with respect to the lever.

6. (New) The actuator assembly as claimed in claim 2, wherein the actuator further comprises: an actuator rod that travels forward or backward causing the actuator to pivot about the hinge unit.

7. (New) The actuator assembly as claimed in claim 1, wherein the actuator further comprises: a link coupled with the first bracket at one end and coupled with the actuator at an other end thereof.

8. (New) The actuator assembly as claimed in claim 7, wherein the actuator further comprises: an actuator rod provided with a yoke connected to the other end of the link.

9. (New) The actuator assembly as claimed in claim 1, further comprises: a drop link having first and second ball joints,

wherein the drop link is coupled to the first bracket by the first ball joint and coupled to the actuator by the second ball joint.